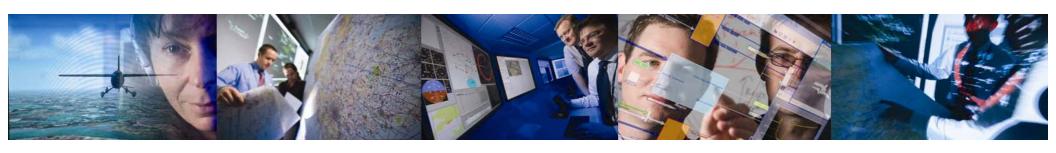


# UK Autonomous Systems Technology Validation Programme

Lambert Dopping-Hepenstal, FREng ASTRAEA Programme Director ICAS Workshop, 24th September 2007





- What is ASTRAEA?
- Who is involved?
- How is it addressing the challenge?
- Where have we got to?
- Where next?



#### What is ASTRAEA?

## A collaborative research and validation programme

- To enable the opening up of the UK and European airspace to the routine use of autonomous Unmanned Aircraft Systems (UAS), without the need for special, restrictive conditions of operation, through the development and demonstration of technologies and operating procedures.
- A key element of the National Aerospace Technology Strategy to build on the collective capability of UK plc in the realm of aerospace technology



#### Who is involved?

# A £32 million partnership, jointly funded by industry and the public sector

- > BERR / TSB
- > Regions
- Welsh Assembly Govt
- Scottish Enterprise
- SEEDA
- SWRDA
- NWDA

- > Industry
- Agent Oriented Software
- BAE Systems
- EADS
- Flight Refuelling
- QinetiQ
- Rolls-Royce
- Thales

- > Universities
- Cranfield
- Lancaster
- Leicester
- Loughborough
- Sheffield
- West of England

> CAA

40+ Subcontract SMEs and Universities



#### 'Hard' Technical Drivers

- Highly dependable and secure communications (spectrum/bandwidth)
- Sense & Avoidance of other air traffic (non-cooperative) in air and ground
- Dependable ability to monitor, comply and respond to ATC instructions
- Integration of Sense & Avoidance with existing co-operative systems (e.g. TCAS) and air traffic management
- Highly dependable navigation, including the ability to re-route
- Management of faults to a similar level afforded by pilots
- Dependable flight termination in emergencies (including forced landings)
- Obstacle / Terrain avoidance
- Affordability

Source: JAA/EUROCONTROL UAV Task Force



#### 'Soft' Drivers

#### Regulatory (e.g.)

Acceptance that visual signals are unnecessary

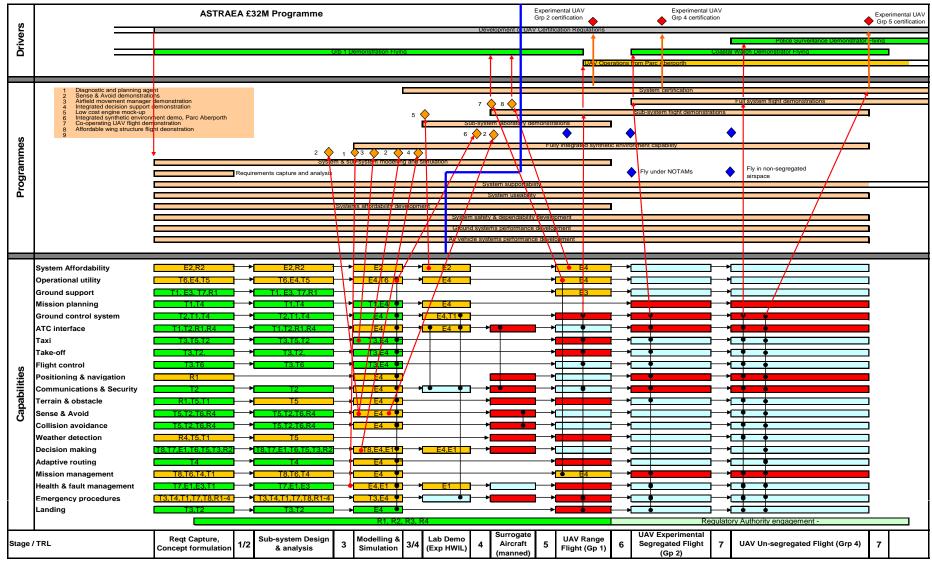
#### **Procedures / Training**

- Submission, maintenance and closure of flight plans
- Pilot licensing and training
- Ground handling and maintenance
- Preventing disruption of UAV operator
- Establishing pilot fatigue criteria
- Establishing weather minima

Source: JAA/EUROCONTROL UAV Task Force

# **Programme Roadmap**











# What is Autonomy?

# Automation has fixed choice points and a number of fixed alternatives

- e.g. bank of lifts in a building
- 'black box' implementation logic not visible to the human, but simple
- does not take account of current circumstances

The concept of automation has a long history, evolving from 19th century mechanical industrial control technology

# Autonomy, a contemporary concept, is distinguished on the other hand by need for decisions to be made at any time. Such a system

- makes "rational" decisions
- has a view of current situation
- evaluates potential courses of action in light of this appreciation
- > needs to expose its reasoning process to humans



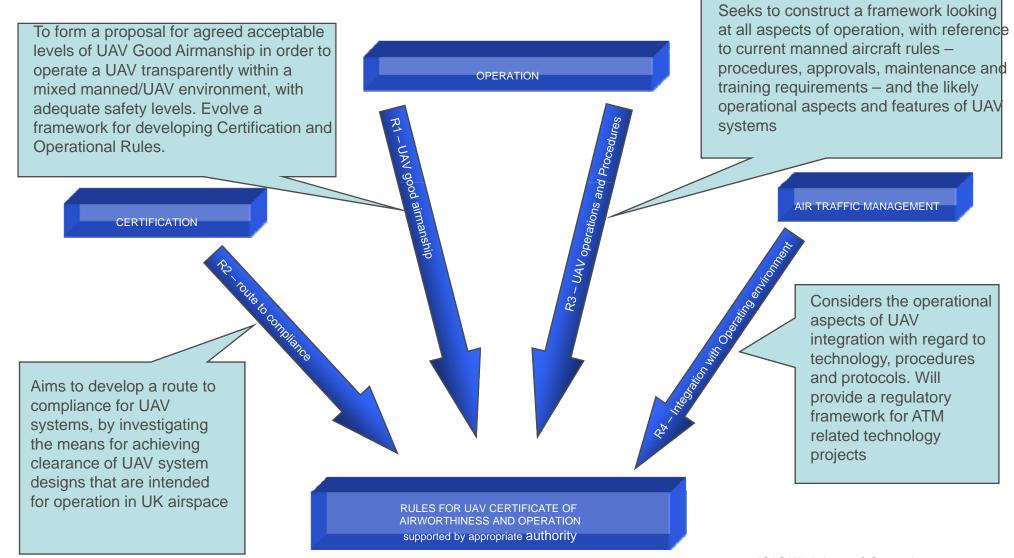
# Regulatory framework and procedures

For UAS to be routinely used in place of manned aircraft for common operational missions, the current regulatory framework requires re-interpretation

- UAS should operate at an equivalent level of safety within the existing Air Traffic Management (ATM) structure.
- UAS should show an equivalent level of compliance with ATM and Communications, Navigation and Surveillance (CNS) requirements.
- The provision of Air Traffic Services to a UAS must be transparent to the controller and other airspace users.



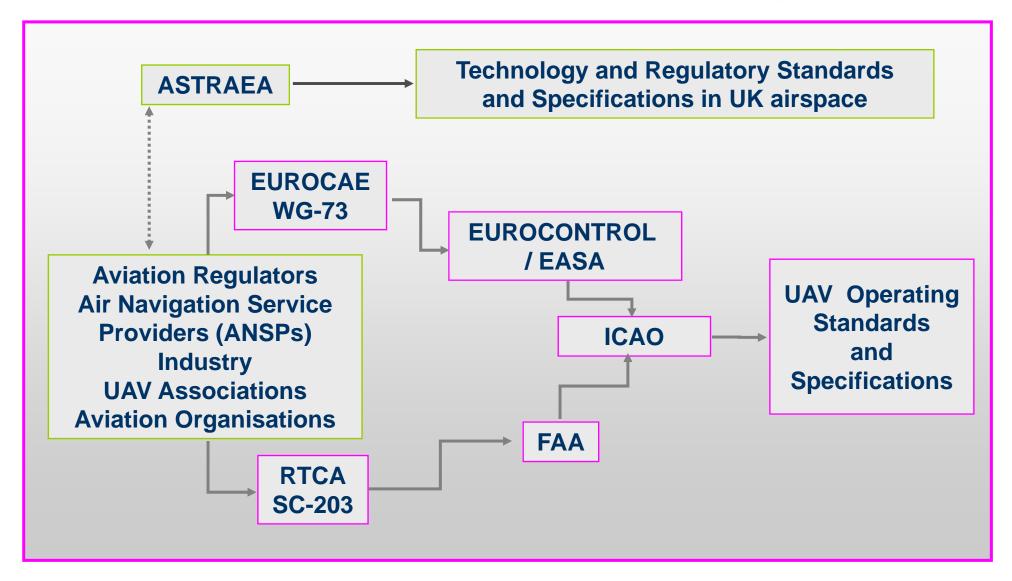
# Regulatory processes



ICAS Workshop 24th September 2007

## **Engaging wider Regulation Authorities**







# **Capability Developments**

Ground operations and human system interface (T1)

**Communications & Air Traffic Control (T2)** 

**UAV** handling (T3)

Adaptive routeing (T4)

**Collision avoidance systems (T5)** 

Multiple air vehicle integration (T6)

**Prognostics & health management (T7)** 

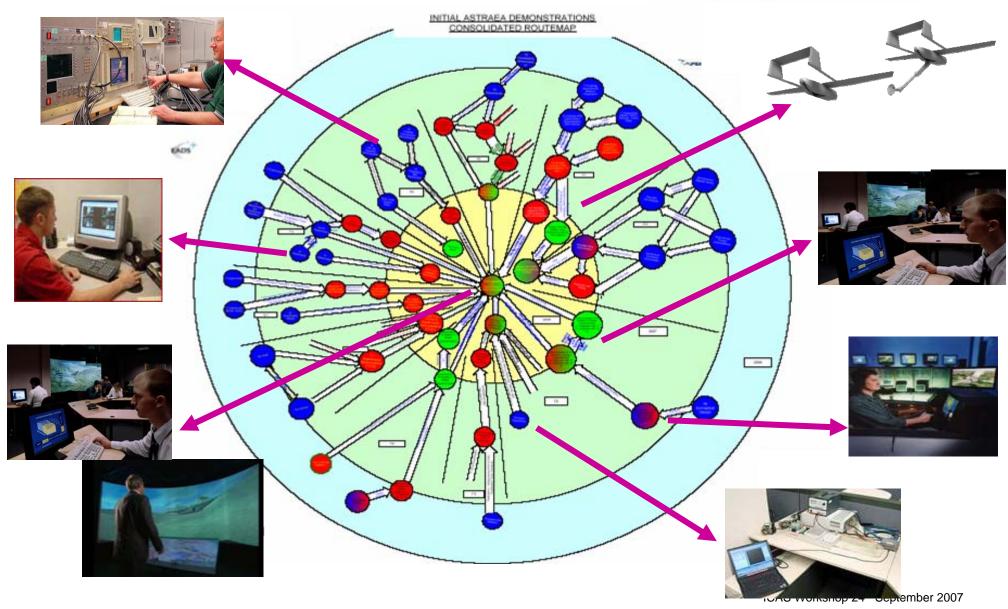
**Decision making (T8)** 

Propulsion & power systems (E1)

Qualification of affordable processes (E2)

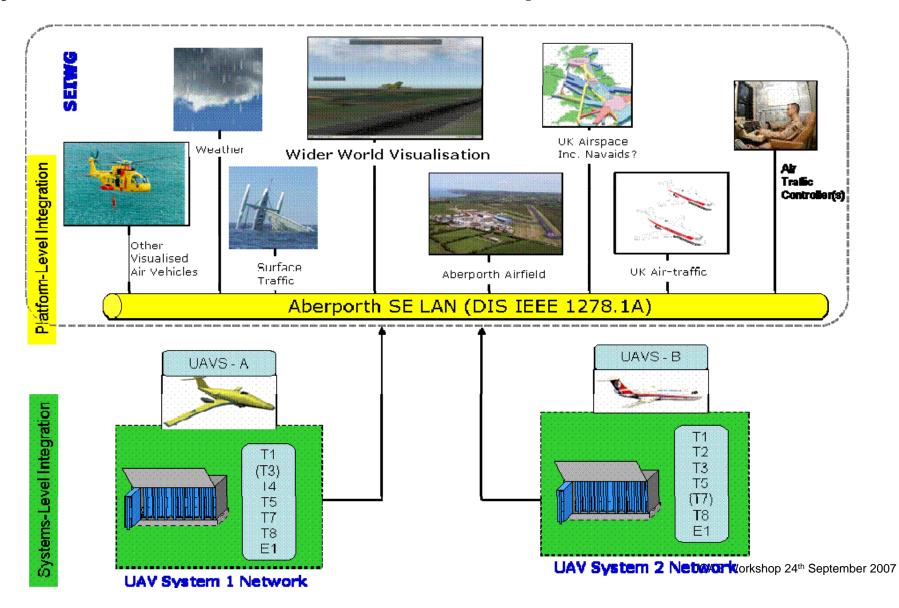
# **Demonstrations**







## Synthetic Environment at Parc Aberporth



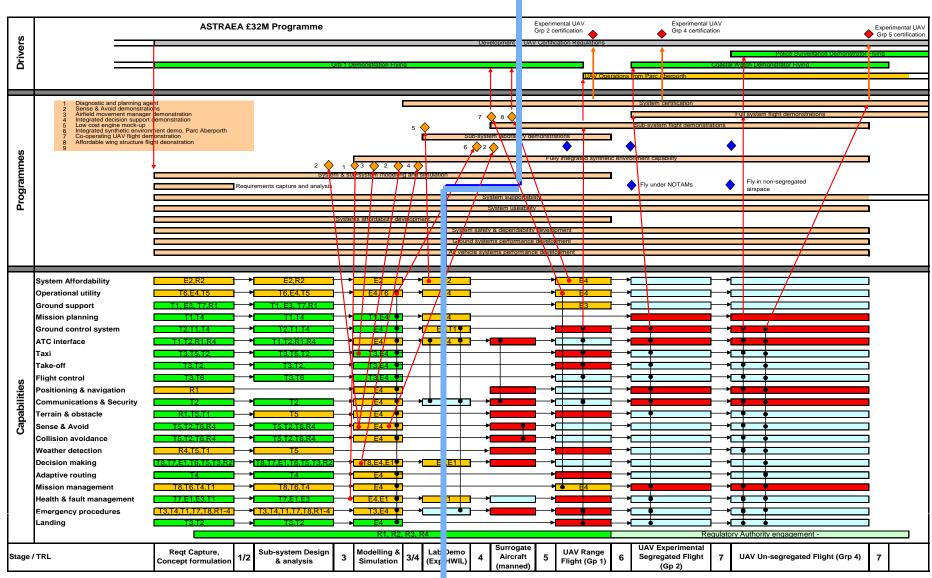


## **ASTRAEA Achievements**

The first year of activity saw the following tasks completed:		
		Requirements captured for technology projects
		Established a co-ordinated set of practical and synthetic demonstrations
		Identified a roadmap to achieve the ultimate goal
		Input to CAP 722 Issue 4
		Initial demonstrations
ear 2 and 3 will:		
		Mature the understanding of the route to routine operation of UAS by development of technology and engagement with regulators
		Undertake further practical and synthetic demonstrations
		Identify the critical areas still to be addressed in a future phase

# **Next step**









#### Website www.ASTRAEA.aero





UK Autonomous Systems Technology Validation Programme







#### The next big aerospace market

#### ASTRAEA Programme Unmanned Systems National Conference

Bristol, 17 October 2007

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#### Where and wheel

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Karen Antoniolik, WEAF (ASTRACA), Lind S. 19 Sentis Court, Windrell Road, Cleveston, Sorth Sprannet 8511 6100 Fax: +44 (STUTS 87385)

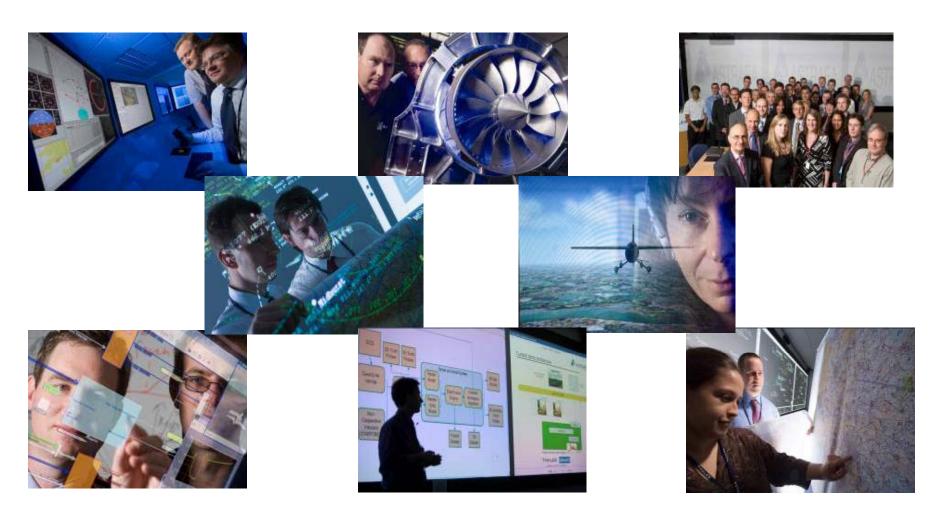
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www.astraea.aero

# First ASTRAEA Conference Bristol, 17<sup>th</sup> October 2007 www.astraea.aero







## Ground operations and human system interface (T1)

Objective: aimed at defining ground-based elements involved in the management of flight operations for civil UAS and providing an understanding of the role of the human in such operations

- Identified operator roles within a civil context (including location, numbers, skills and required toolset)
- Planning, monitoring and control systems capable of supporting autonomous air vehicle operations
- Presentation of decision support information in line with platform-variable autonomy levels









#### **Communications & Air Traffic Control (T2)**

Objective: aimed at the data requirements for autonomous operation, it also addresses the communications technology needed to interact with Air Traffic Control system.

#### **Innovations & outputs**

To define requirements for the first CAA-certified communication system to control the flight of a UAS













#### **UAV** handling (T3)

Objective: developing basic enabling systems for flight control and airfield movement management

- > Airfield movement algorithms for autonomous air vehicles.
- Emergency recovery algorithms for autonomous air vehicles







# **Experimentation and demonstration**

#### Propulsion & power systems (E1)

Objective: to assess, in the absence of a pilot-in-the-loop, the functionality and interface requirements between a typical propulsion system and a modern Aircraft Management System,

- Automate the functionality of the pilot with regard to propulsion & power delivery decision-making
- Develop an autonomous intelligent response to environmental and goal-based inputs







# **Experimentation and demonstration**

#### Qualification of affordable processes (E2)

Objective: to develop affordable and qualifiable processes for the design and manufacture of UAS airframes and engines,

- Use of low-cost, resin-infused composites as flight-qualified primary structure
- > Target of 80% reduction in cost of engine components









#### Multiple air vehicle integration (T6)

Objective: researching of technologies and procedures that will increase UAS utility by enabling safe and affordable task co-operation among multiple air vehicles (UAS or manned) within a common air environment

- Non co-operative autonomous sensing systems
- Integration of 'sense and co-operate' with 'sense and avoid'
- Co-operative multi-vehicle search patterns
- Modeling of wake turbulence effects









#### **Prognostics & health management (T7)**

Objective: aims to provide technology and systems so that UAS can monitor their own state, perform real-time prognosis of immediate and future capabilities and to make decisions on how best to assist optimal mission performance

- Development of innovative hazard identification, reliability analysis, prognostics & health management design tools and methods, and Phased Mission Modelling methods facilitating UAS Contingency Management
- Platform Level PHM Demonstration in a Synthetic Environment
- 'No-harm' flight demonstration













#### **Decision making (T8)**

Objective: to develop a robust and clearable system that will provide onboard decision-making capability for operational UAS

- Demonstration of prototype UAS decision-making system operating within a civil scenario
- A roadmap for certification of decision-making technologies operating in civil airspace













#### Adaptive routeing (T4)

Objective: aimed at developing and implementing an adaptive routeing algorithm for use aboard UAS to aid their use in civil operations

#### **Innovations & outputs**

- Adaptive routeing algorithm for autonomous air vehicles.
- Application for auto-routeing
- Application for setting rules and constraints for adaptive routeing algorithm





BAE SYSTEMS





#### **Collision avoidance systems (T5)**

Objective: to verify the merits of 'sense and avoid' system capabilities to provide a realistic and informed set of options for use by various categories of UAS to support routine operations in all classes of airspace

- Application of technologies (sensors, fusion, avoidance algorithms and decision-making architectures) to identify 'sense and avoid' system solutions for various UAS platforms
- Synthetic demonstration of unmanned air systems 'sense and avoid' with rule-based decision-making capabilities













# Where is ASTRAEA taking us?

The first year of activity saw the following tasks completed:			
	Requirements captured for technology projects		
	Established a co-ordinated set of practical and synthetic demonstrations		
	Identified a roadmap to achieve the ultimate goal		
	Regulatory engagement plans drafted		
	Initial demonstrations		
Year 2 and 3 will:			
	Mature the understanding of the route to routine operation of UAS by development of technology and engagement with regulators		
	Culminate in a series of practical and synthetic demonstrations		
	Identify the critical areas still to be addressed in a future phase		